



## Simple Nonlinear Regression

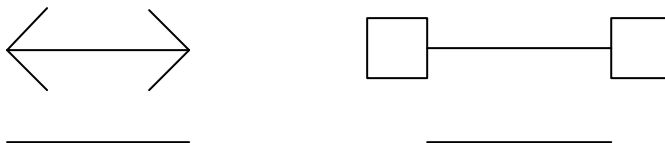
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## Müller-Lyer-Figure and Baldwin-Figure

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**Figure 8.1.** Müller-Lyer-Figur (left) and Baldwin-Figure (right). For the purpose of a direct comparison, the lines with the same length but without the context stimulus are presented below each figure.



## Stevens' Power Law III

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- How can the Stevens' Power Law be tested empirically, i.e. how to test if the dependency really linear regressive?
- How does the perception depend on context stimulus?

Before we can answer these questions we have to introduce further concepts: the linear quasi-regression and the simple nonlinear regression



## Linear Quasi-Regression: Definition

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### Definition 8.1

Let  $X$  and  $Y$  be numerical random variables of a common probability space, and both with a positive and finite variance. The linear function  $Q(Y | X) = \alpha_0 + \alpha_1 \cdot X$  of  $X$  is called *linear Quasi-Regression*, if for the residual

$$\mathbf{n} := Y - (\alpha_0 + \alpha_1 \cdot X), \quad \alpha_0, \alpha_1 \in \mathbb{R},$$

the following equations hold:

$$E(\mathbf{n}) = 0,$$

$$\text{Cov}(\mathbf{n}, X) = 0.$$



## Linear Quasi-Regression: Notes

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The variable  $Y$  is also defined as the sum of a linear function of  $X$  and the error variable  $n$ . This can be shown by transforming the equation to:

$$Y = \alpha_0 + \alpha_1 \cdot X + n.$$



## Linear Quasi-Regression: Properties of the Residual

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$$E(n) = 0$$

$$\text{Cov}(n, X) = 0,$$

However

$$E(n | X) = 0$$

does not necessarily hold.



## Linear Quasi-Regression: Alternative Definition

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### Definition 8.2.

Under the conditions given in definition 8.1 the *linear quasi regression of  $Y$  on  $X$*  can be defined as the linear function of  $X$ , that minimizes the following function of the real-valued  $a_0$  and  $a_1$ :

$$LS(a_0, a_1) = E[(Y - (a_0 + a_1 \cdot X))^2]. \quad \text{least squares criterion}$$

Those numbers  $a_0$  and  $a_1$ , for which the function  $LS(a_0, a_1)$  is a minimum, are denoted by  $\alpha_0$  and  $\alpha_1$ . The linear quasi regression is then defined by:

$$Q(Y|X) := \alpha_0 + \alpha_1 \cdot X.$$



## Linear Quasi-Regression: Identification of Coefficients

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Both definitions of the linear quasi-regression imply the same equations for the coefficients of the linear quasi-regression. They are identical to the equations for the coefficients of the (real) linear regression:

$$\alpha_0 = E(Y) - \alpha_1 \cdot E(X),$$

$$\alpha_1 = \text{Cov}(X, Y) / \text{Var}(X).$$

The identification of the coefficient of determination of the linear quasi-regression is also identical:

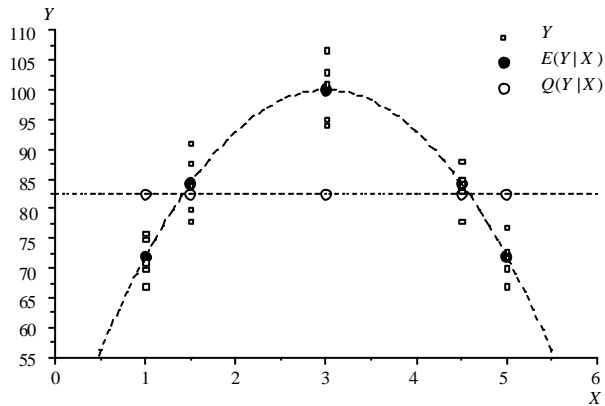
$$Q_{Y|X}^2 := \frac{\alpha_1^2 \text{Var}(X)}{\text{Var}(Y)} = \text{Kor}(X, Y)^2.$$

Only if  $E(Y|X)$  is really a linear function of  $X$  the coefficient of determination of the linear quasi-regression is a real coefficient of determination.



## Linear Quasi Regression: Illustration

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**Figure 8.2.** Regression and linear Quasi-Regression with parabolic regressive dependency of a variable  $Y$  from a variable  $X$ . The (real) regression is the parabola; the conditional expected values are the solid dots. The linear quasi-regression is shown by the straight line parallel to the  $X$ -axis with the non-solid dots. The squares are the pairs of values of  $(X, Y)$ .



## Simple Nonlinear Regression: Parameterization as a Polynomial Regression Model

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The example in Figure 8.2 showed a regression, which was not a linear function but a *quadratic function*

$$E(Y | X) = \alpha_0 + \alpha_1 \cdot X + \alpha_2 \cdot X^2,$$

of  $X$ . In general there can cubic or even polynomials of higher order

$$E(Y | X) = \alpha_0 + \alpha_1 \cdot X + \alpha_2 \cdot X^2 + \dots + \alpha_{n-1} \cdot X^{n-1}.$$

In this case however, the regressor  $X$  has to have at least  $n$  different values, because you can always put a polynomial of the order  $(n-1)$  through  $n$  points.



## Simple Nonlinear Regression: Parameterization as a Means Regression Model I

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If the regressor  $X$  of a regression  $E(Y|X)$  has only  $n$  different values  $x_1, \dots, x_n$  the regression  $E(Y|X)$  can be parameterized as a means model. First, we need  $n$  indicator variables:

$$I_i = \begin{cases} 1, & \text{if } X = x_i \\ 0, & \text{otherwise} \end{cases}, \quad i = 1, \dots, n.$$

The variables  $I_i$  (so-called dummy variables) indicate with the value 1, if the regressor  $X$  takes the value  $x_i$ . Note that these indicator variables  $I_i$  are functions of  $X$ , and that all  $I_1, \dots, I_n$  contain the same information as the regressor  $X$ . That is:  $E(Y|X) = E(Y|I_1, \dots, I_n)$ . Hence we can use both notations.



## Simple Nonlinear Regression: Parameterization as a Means Regression Model II

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The following parameterization represents a saturated model:

$$E(Y|X) = \mu_1 \cdot I_1 + \dots + \mu_n \cdot I_n.$$

The usage of the symbols  $\mu_i$  makes sense, because the  $\mu_i$  represent the conditional expected values, i.e.

$$\mu_i = E(Y|X = x_i), \quad \text{for } i = 1, \dots, n.$$

This can be easily be shown by

$$\begin{aligned} E(Y|X = x_1) &= \mu_1 \cdot 1 + \mu_2 \cdot 0 + \dots + \mu_n \cdot 0 &&= \mu_1, \\ E(Y|X = x_2) &= \mu_1 \cdot 0 + \mu_2 \cdot 1 + \mu_3 \cdot 0 + \dots + \mu_n \cdot 0 &&= \mu_2, \\ &\vdots \\ E(Y|X = x_n) &= \mu_1 \cdot 0 + \mu_2 \cdot 0 + \dots + \mu_n \cdot 1 &&= \mu_n. \end{aligned}$$



## Testing the Linearity of a Regression I

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To test the linearity of a regression  $E(Y|X)$  you first calculate a linear quasi-regression and its coefficient of determination  $Q_{Y|X}^2 = \alpha_1^2 \text{Var}(X) / \text{Var}(Y)$  with a program for simple linear regression. Then you calculate the regression  $E(Y|X)$  and the coefficient of determination  $R_{Y|X}^2$  via a saturated parameterization. The test of the linearity of the regression is done by comparing  $Q_{Y|X}^2$  with  $R_{Y|X}^2$ . If the regression  $E(Y|X)$  is linear, then:

$$H_0: R_{Y|X}^2 - Q_{Y|X}^2 = 0$$



## Testing the Linearity of a Regression II

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The test of linearity can be accomplished by the following test statistic:

$$F = \frac{(\hat{R}_{Y|X_1, \dots, X_n}^2 - \hat{Q}_{Y|X}^2)/(n-m)}{(1 - \hat{R}_{Y|X_1, \dots, X_n}^2)/(N-n)}$$

where  $n$  is the number of parameters of the saturated parameterization,  $m$  the number of parameters of the restricted, the quasi linear parameterization and  $N$  the number of the sample size.



## Logistic Regression I

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If  $Y$  is a dichotomous regressand with values 0 and 1, then the regression  $E(Y | X)$  is also the conditional probability function  $P(Y = 1 | X)$ . If  $X$  is not a dichotomous, but a continuous variable, then the regression  $E(Y | X)$  can not be parameterized as a linear regression, because a straight line is inconsistent with the range  $[0, 1]$  of a (conditional) probability.

In this case the logistic linear parameterization is often used:

$$P(Y = 1 | X) = \frac{\exp(\gamma_0 + \gamma_1 X)}{1 + \exp(\gamma_0 + \gamma_1 X)}$$



## Logistic Regression III

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In the linear case, the *logit* may be written:

$$\ln \frac{P(Y=1 | X)}{P(Y=0 | X)} = \gamma_0 + \gamma_1 X$$



## Logistic Regression II

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If  $X$  is continuous and  $Y$  is dichotomous the regression might not be a logistic linear one. The more general case would be a polynomial parameterization:

$$P(Y = 1|X) = \frac{\exp(\gamma_0 + \gamma_1 X + \gamma_2 X^2 + \dots + \gamma_{n+1} X^{n+1})}{1 + \exp(\gamma_0 + \gamma_1 X + \gamma_2 X^2 + \dots + \gamma_{n+1} X^{n+1})}.$$



## Logistic Regression III

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The equation

$$P(Y = 1 | X) = \frac{\exp(\lambda_1 I_1 + \lambda_2 I_2 + \dots + \lambda_n I_n)}{1 + \exp(\lambda_1 I_1 + \lambda_2 I_2 + \dots + \lambda_n I_n)}$$

is the saturated parameterisation if the regressor  $X$  has only  $n$  different values  $x_1, \dots, x_n$ .